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PowerFlex 40 Adjustable Frequency AC Drive

Bulletin Number 22B

Firmware Revision 1.xx...7.xx

Allen-Bradley
by ROCKWELL AUTOMATION

User Manual

Original Instructions

Installation/Wiring

This chapter provides information on mounting and wiring the PowerFlex 40 drive.

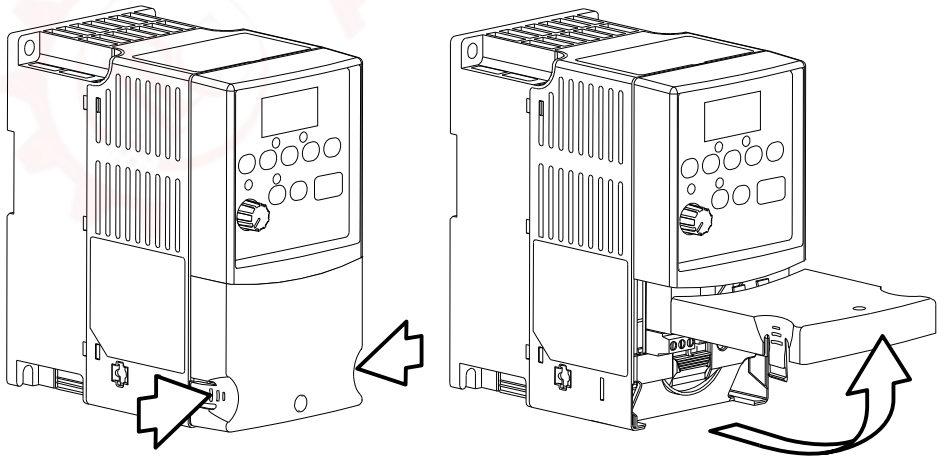
Most start-up difficulties are the result of incorrect wiring. Every precaution must be taken to assure that the wiring is done as instructed. All items must be read and understood before the actual installation begins.

ATTENTION: The following information is merely a guide for proper installation. Rockwell Automation, Inc. cannot assume responsibility for the compliance or the noncompliance to any code, national, local or otherwise for the proper installation of this drive or associated equipment. A hazard of personal injury and/or equipment damage exists if codes are ignored during installation.

Opening the Cover

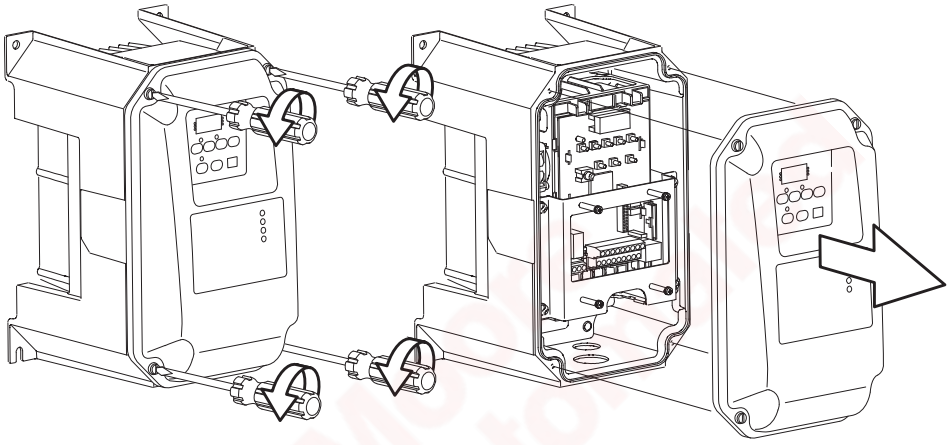
IP20, NEMA/UL Type Open

1. Press and hold in the tabs on each side of the cover.
2. Pull the cover out and up to release.



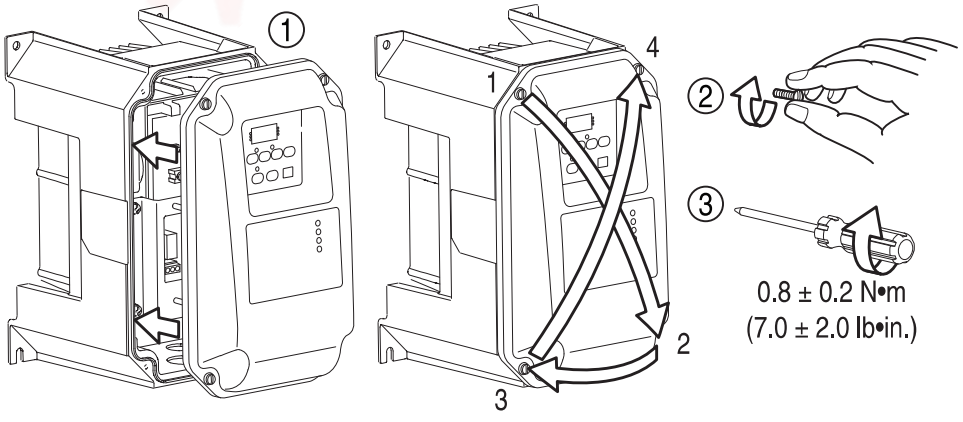
IP66, NEMA/UL Type 4X

1. Loosen the four captive cover screws.
2. Pull cover straight off chassis.



IP66, NEMA/UL Type 4X Cover Installation

1. Squarely align the cover on the chassis.
2. Lightly tighten the four captive cover screws.
3. Torque the cover screws using an alternating pattern.



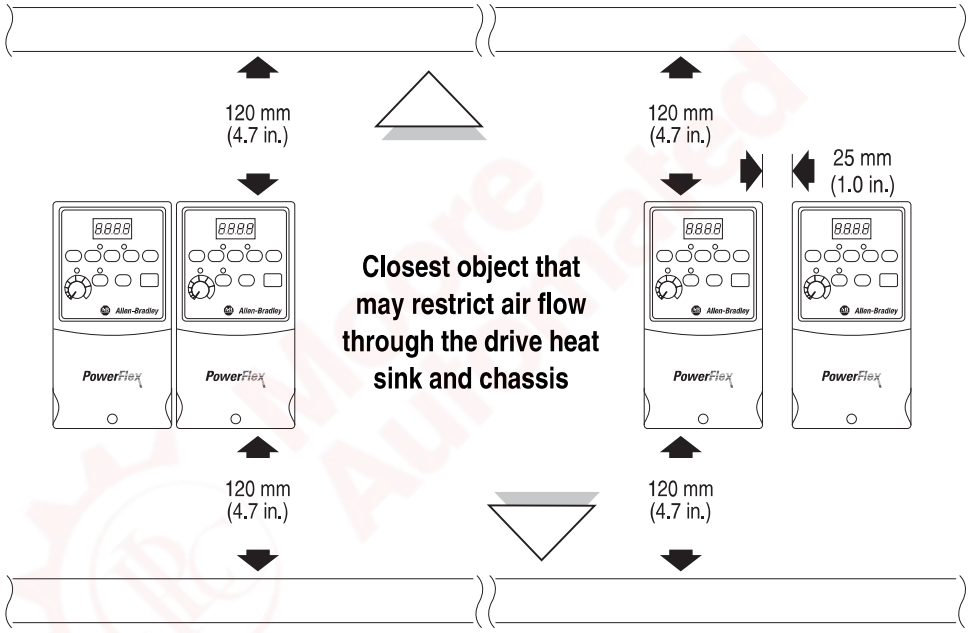
Mounting Considerations

- Mount the drive upright on a flat, vertical and level surface.

Frame	Screw Size	Screw Torque	DIN Rail
B	M4 (#8...32)	1.56...1.96 N•m (14...17 lb•in)	35 mm (1.377 in.)
C	M5 (#10...24)	2.45...2.94 N•m (22...26 lb•in)	–
B (IP66, Type 4X)	M6 (#12...24)	3.95...4.75 N•m (35...42 lb•in)	–

- Protect the cooling fan by avoiding dust or metallic particles.
- Do not expose to a corrosive atmosphere.
- Protect from moisture and direct sunlight.

Minimum Mounting Clearances



Mounting Option A
No clearance is required between drives.

Mounting Option B

Ambient Operating Temperatures

Table 1 – Enclosure and Clearance Requirements

Ambient Temperature		Enclosure Rating	Minimum Mounting Clearances
Minimum	Maximum		
-10 °C (14 °F)	40 °C (104 °F)	IP20, NEMA/UL Type Open	Use Mounting Option A
		IP66, NEMA/UL Type 4X	Use Mounting Option A
		IP30, NEMA/UL Type 1(1)	Use Mounting Option B
	50 °C (122 °F)	IP20, NEMA/UL Type Open	Use Mounting Option B

(1) Rating requires installation of the PowerFlex 40 IP30, NEMA/UL Type 1 option kit.

Debris Protection

A plastic top panel is included with the drive. Install the panel to prevent debris from falling through the vents of the drive housing during installation. Remove the panel for IP20, NEMA/UL Type Open applications.

Storage

- Store within an ambient temperature range of -40…+85 °C (-40…+185 °F).
- Store within a relative humidity range of 0…95%, non-condensing.
- Do not expose to a corrosive atmosphere.

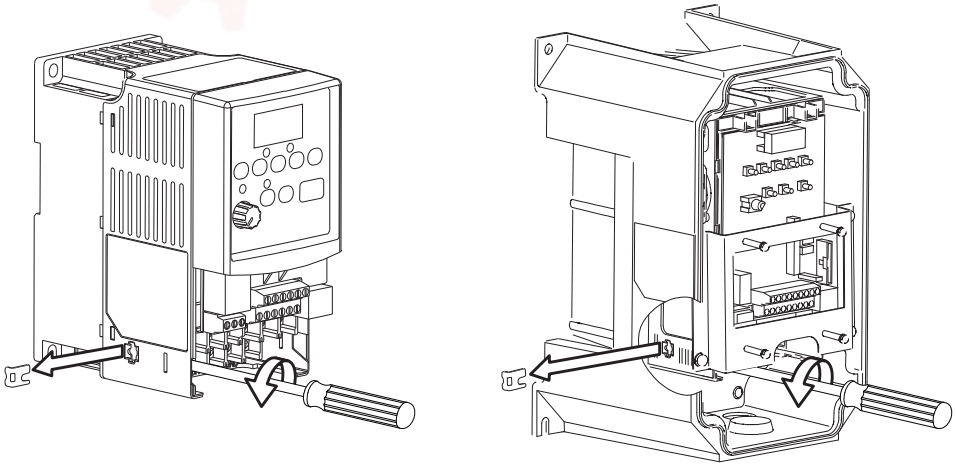
AC Supply Source Considerations

Ungrounded Distribution Systems

ATTENTION: PowerFlex 40 drives contain protective MOVs that are referenced to ground. These devices must be disconnected if the drive is installed on an ungrounded or resistive grounded distribution system.

1. Turn the screw counterclockwise to loosen.
2. Pull the jumper completely out of the drive chassis.
3. Tighten the screw to keep it in place.

Figure 1 – Jumper Location (Typical)



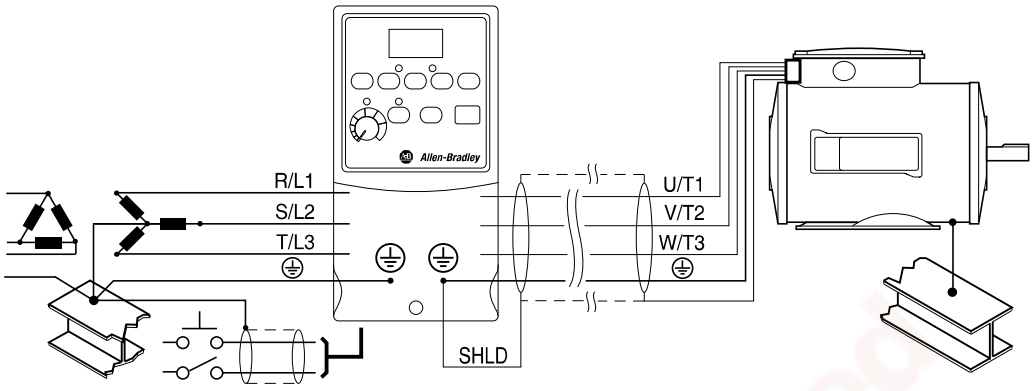
IP20, NEMA/UL Type Open **IP66, NEMA/UL Type 4X**

Important: Tighten screw after jumper removal.

General Grounding Requirements

The drive Safety Ground - ⏚ (PE) must be connected to system ground. Ground impedance must conform to the requirements of national and local industrial safety regulations and/or electrical codes. The integrity of all ground connections should be periodically checked.

Figure 3 – Typical Grounding



Ground Fault Monitoring

If a system ground fault monitor (RCD) is to be used, only Type B (adjustable) devices should be used to avoid nuisance tripping.

Safety Ground - ⏚ (PE)

This is the safety ground for the drive that is required by code. One of these points must be connected to adjacent building steel (girder, joist), a floor ground rod or bus bar. Grounding points must comply with national and local industrial safety regulations and/or electrical codes.

Motor Ground

The motor ground must be connected to one of the ground terminals on the drive.

Shield Termination - SHLD

Either of the safety ground terminals located on the power terminal block provides a grounding point for the motor cable shield. The **motor cable** shield connected to one of these terminals (drive end) should also be connected to the motor frame (motor end). Use a shield terminating or EMI clamp to connect the shield to the safety ground terminal. The conduit box option may be used with a cable clamp for a grounding point for the cable shield.

When shielded cable is used for **control and signal wiring**, the shield should be grounded at the source end only, not at the drive end.

RFI Filter Grounding

Using single phase drives with integral filter, or an external filter with any drive rating, may result in relatively high ground leakage currents. Therefore, the **filter must only be used in installations with grounded AC supply systems and be permanently installed and solidly grounded** (bonded) to the building power distribution ground. Ensure that the incoming supply neutral is solidly connected (bonded) to the same building power distribution ground. Grounding must not rely on flexible cables and should not include any form of plug or socket that would permit inadvertent disconnection. Some local codes may require redundant ground connections. The integrity of all connections should be periodically checked.

Fuses and Circuit Breakers

The PowerFlex 40 drive does not provide branch short circuit protection. This product should be installed with either input fuses or an input circuit breaker. National and local industrial safety regulations and/or electrical codes may determine additional requirements for these installations.

ATTENTION: To guard against personal injury and/or equipment damage caused by improper fusing or circuit breaker selection, use only the recommended line fuses/circuit breakers specified in this section.

Fusing

The PowerFlex 40 drive has been UL tested and approved for use with input fuses. The ratings in the table that follows are the minimum recommended values for use with each drive rating. The devices listed in this table are provided to serve as a guide.

Bulletin 140M/140MT (Self-Protected Combination Controller)/ UL489 Circuit Breakers

When using Bulletin 140M/140MT or UL489 rated circuit breakers, the guidelines listed below must be followed in order to meet the NEC requirements for branch circuit protection.

- Bulletin 140M/140MT can be used in single and group motor applications.
- Bulletin 140M/140MT can be used up stream from the drive **without** the need for fuses.

Start Up

This chapter describes how to start up the PowerFlex 40 drive. To simplify drive setup, the most commonly programmed parameters are organized in a single Basic Program Group.

ATTENTION: Power must be applied to the drive to perform the following start-up procedures. Some of the voltages present are at incoming line potential. To avoid electric shock hazard or damage to equipment, only qualified service personnel should perform the following procedure. Thoroughly read and understand the procedure before beginning. If an event does not occur while performing this procedure, **Do Not Proceed**. **Remove All Power** including user supplied control voltages. User supplied voltages may exist even when main AC power is not applied to the drive. Correct the malfunction before continuing.

Prepare For Drive Start-Up

Before Applying Power to the Drive

❑ **1.** Confirm that all inputs are connected to the correct terminals and are secure.

❑ **2.** Verify that AC line power at the disconnect device is within the rated value of the drive.

❑ **3.** Verify that any digital control power is 24 volts.

❑ **4.** Verify that the Sink (SNK)/Source (SRC) Setup DIP Switch is set to match your control wiring scheme.

Important: The default control scheme is Source (SRC). The Stop terminal is jumpered (I/O Terminals 01 and 11) to allow starting from the keypad. If the control scheme is changed to Sink (SNK), the jumper must be removed from I/O Terminals 01 and 11 and installed between I/O Terminals 01 and 04.

❑ **5.** Verify that the Stop input is present or the drive will not start.

Important: If I/O Terminal 01 is used as a stop input, the jumper between I/O Terminals 01 and 11 must be removed.

Applying Power to the Drive

❑ **1.** Apply AC power and control voltages to the drive.

❑ **2.** Familiarize yourself with the integral keypad features before setting any Program Group parameters.

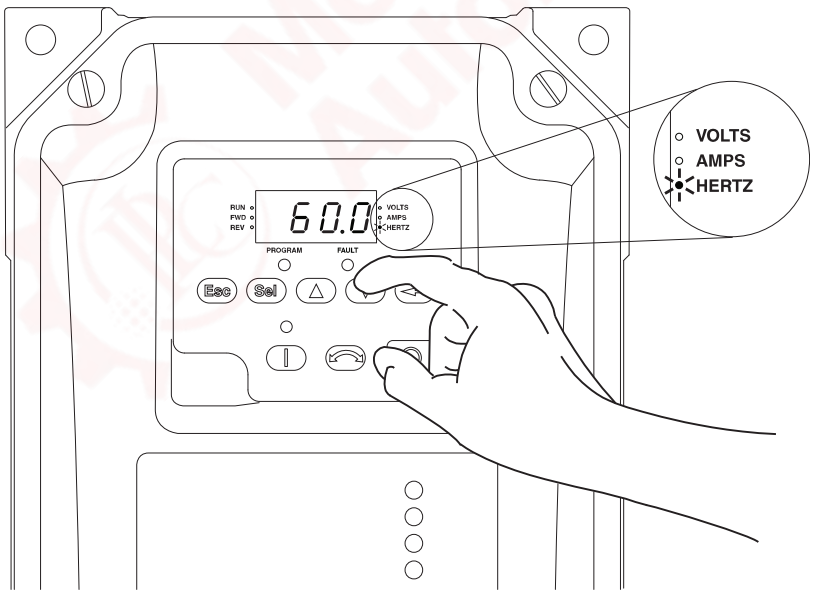
Start, Stop, Direction, and Speed Control

Factory default parameter values allow the drive to be controlled from the integral keypad. No programming is required to start, stop, change direction, and control speed directly from the integral keypad.

Important: To disable reverse operation, see A095 [Reverse Disable].

Changing the Speed Reference of an IP66, NEMA/UL Type 4X rated drive

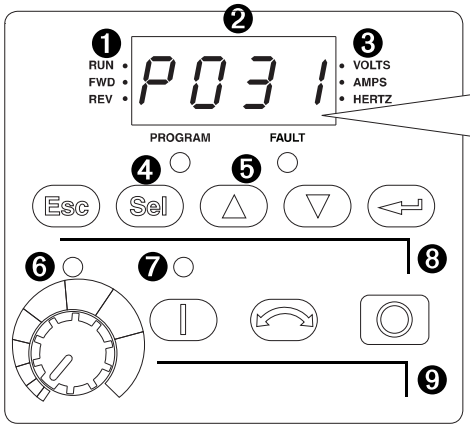
When a Display Group parameter, for example, d001 [Output Freq] is displayed, and P038 [Speed Ref] is set to A069 [Internal Freq], you can change the internal frequency using the Up Arrow and Down Arrow keys.



When the internal frequency is being adjusted, its value is displayed and the Hertz LED flashes. Any changes are saved immediately. The display then returns to the Display Group parameter previously shown.

TIP: By default, the speed reference of an IP66, NEMA/UL Type 4X rated drive is set to the internal frequency, A069 [Internal Freq].

Integral Keypad



Menu	Description
d	**Display Group (View Only)** Consists of commonly viewed drive operating conditions.
P	**Basic Program Group** Consists of most commonly used programmable functions.
A	**Advanced Program Group** Consists of remaining programmable functions.
F	**Fault Designator** Consists of list of codes for specific fault conditions. Displayed only when fault is present.

No.	LED	LED State	Description
❶	Run/Direction Status	Steady Red	Indicates drive is running and commanded motor direction.
		Flashing Red	Drive has been commanded to change direction. Indicates actual motor direction while decelerating to zero.
❷	Alphanumeric Display	Steady Red	Indicates parameter number, parameter value, or fault code.
		Flashing Red	Single digit flashing indicates that digit can be edited. All digits flashing indicates a fault condition.
❸	Displayed Units	Steady Red	Indicates the units of the parameter value being displayed.
❹	Program Status	Steady Red	Indicates parameter value can be changed.
❺	Fault Status	Flashing Red	Indicates drive is faulted.
❻	Pot Status	Steady Green	Indicates potentiometer on Integral Keypad is active.(1)
❼	Start Key Status	Steady Green	Indicates Start key on Integral Keypad is active. The Reverse key is also active unless disabled by A095 [Reverse Disable].

No.	Key	Name	Description
❽	Esc	Escape	Back one step in programming menu. Cancel a change to a parameter value and exit Program Mode.
	Sel	Select	Advance one step in programming menu. Select a digit when viewing parameter value.
	△ ▽	Up Arrow Down Arrow	Scroll through groups and parameters. Increase/decrease the value of a flashing digit. Used to adjust internal frequency of IP66, NEMA/UL Type 4X rated drives *only* when a Display Group parameter is shown and P038 [Speed Reference] is set to internal frequency, A069 [Internal Freq].
	↵	Enter	Advance one step in programming menu. Save a change to a parameter value.
❾		Potentiometer(1)	Used to control speed of drive. Default is active. Controlled by parameter P038 [Speed Reference].
		Start	Used to start the drive. Default is active. Controlled by parameter P036 [Start Source].
		Reverse	Used to reverse direction of the drive. Default is active. Controlled by parameters P036 [Start Source] and A095 [Reverse Disable].
		Stop	Used to stop the drive or clear a fault. This key is always active. Controlled by parameter P037 [Stop Mode].

(1) IP66, NEMA/UL Type 4X rated drives are not equipped with a potentiometer.

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