

3500/72M Recip Rod Position Monitor

Datasheet

Cordant™

146478 Rev. M

Description

The four-channel Bently Nevada™ 3500/72M Recip Rod Position Monitor accepts input from proximity transducers, conditions the signal to provide dynamic and static position measurements, and compares the conditioned signals with user-programmable alarms.

Each channel, depending on how you configure it, typically conditions its input signal to generate various parameters called measured values.

Use the 3500 Rack Configuration Software to:

- Configure alert setpoints for each active measured value and danger setpoints for any two of the active measured values.
- Protect reciprocating compressors by continuously comparing monitored parameters against configured alarm setpoints to display alarms and trigger relays, if needed.
- Monitor the condition of essential reciprocating compressor machinery.



The monitor channels are programmed in pairs and can perform up to two functions at a time. For example, channels 1 and 2 can perform one function while channels 3 and 4 perform another or the same function.

The 3500/72M Recip Rod Position Monitor meets API 618 requirements for reciprocating compressors. It measures:

- Rod position
- Rod drop
- Hyper-compressor



Specifications

Inputs

Signal	Accepts from 1 to 4 proximity probe signals
Input Impedance	10 k Ω
Nominal Scale Factor	
Rod Position	0.79 mV/ μ m (20 mV/mil), 3.94 mV/ μ m (100 mV/mil), or 7.87 mV/ μ m (200 mV/mil)
Rod Position 2	3.94 mV/ μ m (100 mV/mil), or 7.87 mV/ μ m (200 mV/mil)
Rod Drop	3.94 mV/ μ m (100 mV/mil), or 7.87 mV/ μ m (200 mV/mil)
Hyper Compressor	3.94 mV/ μ m (100 mV/mil), or 7.87 mV/ μ m (200 mV/mil)
Power Consumption	7.7 watts, nominal

Outputs

Front Panel LEDs	
OK LED	Indicates when the Recip Rod Position Monitor is operating properly.
TX/RX LED	Indicates when the Recip Rod Position Monitor is communicating with other modules in the 3500 rack.
Bypass LED	Indicates when the Recip Rod Position Monitor is in Bypass Mode.
Front Buffered Outputs	
Buffered Transducer Outputs	The front of each monitor has one coaxial connector for each channel. Each connector is short-circuit protected.

Output Impedance	510 Ω
Transducer Power Supply	-24 Vdc

Data Values

The 3500/72M Recip Rod Position Monitor returns the following data values from measurements used to monitor the machine:

Rod Position Single Channel	Position Magnitude, Position Angle, Crank Angle, Pk-Pk Amplitude, Gap, 1X Amplitude, Not 1X Amplitude, 2X Amplitude
Rod Position Single 2 Channel	Pk-Pk Amplitude Position Magnitude Position Angle Crank Angle Gap Average Piston Position Instantaneous Piston Position Instantaneous Probe Gap
Rod Position Pair Channel	Position Magnitude, Position Angle, Crank Angle, Pk-Pk Amplitude, Gap, 1X Amplitude, Not 1X Amplitude, 2X Amplitude
Rod Position Pair 2 Channel	Pk-Pk Amplitude Position Magnitude Position Angle Crank Angle Gap Average Piston Position Instantaneous Piston Position Instantaneous Probe Gap
Rod Drop Channel	Average Piston Position, Average Probe Gap, Instantaneous Piston Position, Instantaneous Probe Gap

Hyper Channel	Pk-Pk Displacement, Gap, 1X Amplitude, Not 1X Amplitude, 2X Amplitude
---------------	---

Signal Conditioning



Specified at +25°C (+77°F) unless otherwise noted.

Rod Position 2 (Single and Pair) Channels

Frequency Response	
Peak-Peak filter	Fixed 1 Hz to 600 Hz
Gap filter	-3 dB at 0.09 Hz
Average piston position	Fixed 1 Hz to 600 Hz
Accuracy	
Peak-Peak Amplitude	Within ±0.33% of full-scale typical ±1% maximum
Position magnitude	Within ±0.33% of full-scale typical ±1% maximum
Rod Position Angle (paired only)	Within ±1° typical ±3° maximum
Position Crank Angle	Within ±1° typical ±3° maximum
Gap	Within ±0.33% of full-scale typical ±1% maximum
Average piston position	Within ±0.33% of full-scale typical ±1% maximum
Instantaneous piston position	Within ±0.33% of full-scale typical ±1% maximum
Instantaneous piston gap	Within ±0.33% of full-scale typical ±1% maximum

Rod Position Single and Pair Channels

Frequency Response	
Peak-Peak filter	Fixed 1 Hz to 600 Hz
Gap filter	-3 dB at 0.09 Hz
Not 1X filter	Constant Q Notch filter Minimum rejection in stop-band of 34.9 dB over frequency range of 60 cpm to 15.8 times running speed
1X and 2X vector filter	Constant Q Filter Minimum rejection in stopband of 57.7 dB



1X and 2X Vector and Not 1X parameters are valid for machine speeds of 60 cpm to 2130 cpm.

Accuracy	
Position magnitude (direct)	Within ±0.33% of full-scale typical ±1% maximum
Gap	Within ±0.33% of full-scale typical ±1% maximum
1X Amplitude	Within ±0.33% of full-scale typical ±1% maximum
2X Amplitude	Within ±0.33% of full-scale typical ±1% maximum
Pk-Pk Amplitude	Within ±0.33% of full-scale typical ±1% maximum
Not 1X Amplitude	Within ±3.0% of full scale typical
Position Crank Angle	Within ±1° typical ±3° maximum

Accuracy

Rod Position Angle (paired only)	Within $\pm 1^\circ$ typical $\pm 3^\circ$ maximum
----------------------------------	---

Rod Drop Channels

Frequency Response

Average piston position (direct)	Fixed 1 Hz to 600 Hz
Average Gap	-3 dB at 0.09 Hz

Accuracy

Average piston position (direct)	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
Average Gap	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
Instantaneous piston position	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
Instantaneous probe Gap	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum


Hyper Channels

Frequency Response

Peak-Peak filter	Fixed 1 Hz to 600 Hz
Gap filter	-3 dB at 0.09 Hz
Not 1X filter	Constant Q Notch filter Minimum rejection in stop-band of 34.9 dB over frequency range of 60 cpm to 15.8 times running speed

Frequency Response

1X Vector filter	Constant Q filter Minimum rejection in stop-band of 57.7 dB
2X Vector filter	Constant Q filter Minimum rejection in stop-band of 57.7 dB

 1X and 2X Vector and Not 1X parameters are valid for machine speeds of 60 cpm to 2130 cpm.

Accuracy

Peak-Peak magnitude	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
Gap	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
1X Amplitude	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
2X Amplitude	Within $\pm 0.33\%$ of full-scale typical $\pm 1\%$ maximum
Not 1X Amplitude	Within $\pm 0.33\%$ of full-scale typical

Physical

Monitor Module (Main Board)	
Dimensions (Height x Width x Depth)	241.3 mm x 24.4 mm x 241.8 mm (9.50 in x 0.96 in x 9.52 in)
Weight	0.91 kg (2.0 lb)
I/O Modules (non-barrier)	
Dimensions (Height x Width x Depth)	241.3 mm x 24.4 mm x 99.1 mm (9.50 in x 0.96 in x 3.90 in)
Weight	0.20 kg (0.44 lb)
I/O Modules (barrier)	
Dimensions (Height x Width x Depth)	241.3 mm x 24.4 mm x 163.1 mm (9.50 in x 0.96 in x 6.42 in)
Weight	0.46 kg (1.01 lb)

Rack Space Requirements

Monitor	1 full-height front slot
I/O Modules	1 full-height rear slot

Environmental Limits

Operating Temperature	When used with Internal / External Termination Proximator / Seismic I/O Module: -30°C to +65°C (-22°F to +149°F)
	When used with Proximator / Seismic Internal Barrier I/O Module (Internal Termination) 0°C to +65°C (32°F to +149°F)
Storage Temperature	-40°C to +85°C (-40°F to +185°F)
Humidity	95% Non-condensing

Alarms

Alarm Setpoints	Use Rack Configuration Software to set alert levels for each value measured by the monitor and danger setpoints for any two of the values measured by the monitor. Alarms are adjustable from 0 to 100% of full-scale for each measured value. However, when the full-scale range exceeds the range of the transducer, the range of the transducer will limit the setpoint.
Accuracy of alarm setpoints	Within 0.13% of the desired value

Alarm Time Delays

You can program alarm delays using 3500
Rack Configuration Software.

Alert	From one to 60 seconds in one second intervals
Danger	0.1 seconds (nominal) or from one to 60 seconds in one second intervals
Timed OK Channel Defeat	OK Channel defeat is disabled for all Rod Position and Rod Drop configurations. As a hyper-compressor monitor, when both transducers are NOT OK, the monitor issues a Danger alarm immediately.

Compliance and Certifications

FCC

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- This device may not cause harmful interference.
- This device must accept any interference received, including interference that may cause undesired operation.

EMC

European Community Directive:

EMC Directive 2014/30/EU

Standards:

EN 61000-6-2; Immunity for Industrial Environments
EN 61000-6-4; Emissions for Industrial Environments

Electrical Safety

European Community Directive:

LV Directive 2014/35/EU

Standards:

EN 61010-1

RoHS

European Community Directive:

RoHS Directive 2011/65/EU

China RoHS

Cables associated with the product(s) mentioned in this datasheet have an EFUP designation of 15 years, in accordance with SJ/T 11364-2024.



Maritime

DNV GL rules for classification – Ships, offshore units, and high speed and light craft

ABS Rules for Condition of Classification, Part 1

- Steel Vessels Rules
- Offshore Units and Structures